10. Identification

Course title: INE INE410147 – Autonomous Embedded Systems II  
Contact hours: 60 (30 theory, 30 practice)  
Credits: 4  
Professor: Antônio Augusto Fröhlich  
Semester: 2021/2

11. Prerequisites

INE 410144 – Autonomous Embedded Systems I or equivalent knowlege

12. Syllabus

Introduction and review of Autonomous Embedded Systems I. Timing in autonomous systems, time sources and synchronization protocols, timed data. Localization in autonomous systems, global navigation satellite systems, sensor-based localization, sensor fusion. Autonomous system safety, safety models, principles of safe software design and implementation, isolation, virtualization, algorithms, protocols, runtime verification. Project of a real autonomous system and implementation of secure execution environment featuring runtime safety verification.

13. Objectives

Enable students to execute embedded autonomous systems projects, considering both, design and implementation aspects, covering timing, location, safety, isolation, and runtime safety verification.

13.1 Student Learning Outcomes

- Introducing concepts, technologies and tools related to the project of embedded autonomous systems;
- Instructing in the design and implement of embedded autonomous systems components pertaining timing, location, isolation and runtime safety verification;
- Instructing in the integration and validation of embedded autonomous systems components pertaining timing, location, isolation and runtime safety verification;
- Supporting in the development of an autonomous system.

14. Contents

8 - Introduction [2 hours]
9 - Timing in Autonomous Systems [8 hours]
9.1 - Time sources [2 hours]
9.2 - Time synchronization protocols [4 hours]
9.3 - Timed data [2 hours]
10 - Localization in Autonomous Systems [6 hours]
10.1 - Global navigation satellite systems [2 hours]
10.2 - Sensor-based localization [2 hours]
10.3 - Sensor fusion [2 hours]
11 - Safety in Autonomous Systems [12 hours]
11.1 - Safety models [4 hours]
11.2 - Safety model enforcement [8 hours]
11.2.1 - Component isolation and replacement [4 hours]
11.2.2 - Runtime model verification [4 hours]
12 - Autonomous System Project [30 hours]
13 - Discussion and closing [2 hours]

15. Methodology
The theoretic part of the course will be covered in lectures and in discussion of read materials. Lectures will take place face to face in the classroom whenever possible. Alternatively, they will be held synchronously online over the Internet. The practical elements of the course will be carried out asynchronously by students, with access to LISHA being granted whenever necessary. All pertinent materials, activities and grading will be carried out via Moodle. Evaluation and grading will be performed based on the project that will be developed by groups of students. Experts might be invited to lecture on specific topics. Theoretical lectures might take place remotely, via Google Meet, while practical classes we be hold in the lab. Online lectures will not exceed 20 hours.

16. Grading
Grading will be focused on the project of autonomous system conducted by the students organized in groups and working asynchronously, with at least two synchronous presentation at class time. Synchronous seminars related the specific project topics will also be used for grading purposes.

S: Seminar
Pn: Project in n phases of equal weight
Grade = S * 0,3 + P * 0,7

Note: since 50% of the course is practical, there will be no replacement of partial grades as dictated by article 70 of Resolution 17/CUn/97.

17. Time Plan
Seminar: between 3rd and 6th weeks
Project plan: 8th week
Project intermediate check: 12th week
Project final evaluation: 16th week

18. Textbook and Readings
- S. Shalev-Shwartz, S. Shammah, A. Shashua, On a Formal Model of Safe and Scalable Self-driving Cars, Mobileye, 2017.